



# AgroVisionNet Learning Deep Patterns for Resilient Crop Health Analysis

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**ABSTRACT:** Agriculture remains one of the most important sectors for global food production, but crop diseases continue to cause major losses in yield. Traditional ways of detecting diseases depend largely on manual inspection, which is slow and can lead to mistakes. In recent years, deep learning has shown great promise in automating the detection of plant diseases using image analysis. However, most existing methods focus only on visual cues and do not consider environmental factors that significantly affect disease spread. This study introduces AgroVisionNet, an improved deep learning framework that combines image-based disease detection with environmental data like temperature and humidity. The system uses the EfficientNet architecture to extract detailed features from leaf images and then merges these features with climate data through a feature fusion process. This combination allows for more accurate and context-aware disease prediction. The model was trained and tested using a publicly available plant disease dataset. The results show that AgroVisionNet performs better than traditional convolutional neural network models, offering higher accuracy and better adaptability. In addition to identifying diseases, the system also provides preventive advice, which makes it useful for real-world farming. This approach helps in making agriculture more intelligent and sustainable.

**KEYWORDS:** Deep Learning, EfficientNet, Plant Disease Detection, Multimodal Learning, Precision Agriculture, Feature Fusion, Environmental Data Integration, Crop Health Monitoring)

## I. INTRODUCTION

Agriculture is essential for supporting human life and the global economy. One of the biggest challenges for farmers is the early detection and management of plant diseases, which can greatly impact crop yield and quality. Usual methods of disease detection rely on expert knowledge and manual observation, which can be inefficient, biased, and hard to apply over large fields.

With the rise of artificial intelligence, especially deep learning, automated systems for detecting plant diseases have become increasingly popular.

Convolutional neural networks (CNNs) are widely used for image classification, including disease identification from leaf images. Many studies have shown that models like ResNet and traditional CNNs can achieve good accuracy levels. However, these models mainly focus on visual features and often ignore environmental conditions that influence disease development.

Environmental factors such as temperature and humidity play a key role in the growth and spread of plant diseases. Ignoring these conditions may result in inaccurate predictions. Therefore, a system that considers both visual symptoms and environmental data is needed for better decision-making.

In this study, we propose AgroVisionNet, a model that combines image analysis with environmental data. EfficientNet was chosen because it can achieve high accuracy with fewer parameters. Features extracted from images are combined with temperature and humidity data to improve prediction accuracy. The system also provides practical advice for farmers.



The main contributions of this work are as follows:

- Combining environmental data with deep learning for image classification
- Using EfficientNet for more effective feature extraction
- Improving prediction accuracy compared to existing models
- Developing a practical system that provides disease prevention recommendations

This approach connects research with real-world applications by creating a more reliable and intelligent method for plant disease detection.

## II. RELATED WORK

The use of machine learning and deep learning for plant disease detection has increased because these methods can automate diagnosis.

Abbas et al. [2] showed that CNN models like AlexNet and GoogLeNet can achieve 99.35% accuracy on the PlantVillage dataset. However, their work was limited to controlled settings, limiting real-world use.

Later studies improved accuracy by using advanced architectures.

Hughes et al. [7] achieved 99.53% accuracy with VGG, while Himeur et al. [8] applied transfer learning with VGG and ResNet to get 90.4% accuracy. Zampokas et al. [9] proposed a lightweight CNN model with 98.4% accuracy. Although these methods perform well, they rely only on image data and ignore environmental factors.

Object detection models such as Faster R-CNN, R-FCN, and SSD were used by Ahmad et al. [10], achieving an mAP of 86%.

YOLO-based models, like the one by Chen et al. [11], allowed for faster detection but with lower accuracy (~70%). These methods are often computationally expensive and may not work consistently across different datasets.

Chen et al. [12] showed that models like ResNet50 and MobileNetV2 offer a good balance between accuracy and efficiency but also pointed out the lack of environmental data integration.

Other approaches using hyperspectral imaging [13] and advanced learning models [14] offer more insights but are not integrated into a single model.

To address these issues, this work proposes a multimodal approach using EfficientNet.

By combining image data with environmental inputs, the model aims to improve accuracy, reduce complexity, and make the system more suitable for real-time use in plant disease detection.

## III. PROPOSED METHODOLOGY

### A. Overview

The proposed PlantSense system uses two types of input: a leaf image captured by a standard camera or smartphone, and a three-dimensional environmental feature vector that includes air temperature (°C), relative humidity (%), and soil moisture (%).

These inputs are processed through separate branches and fused before multi-task prediction. The system provides three simultaneous predictions—disease class, disease stage, and risk probability—along with recommendations from a knowledge database.

### B. Image Branch — EfficientNet-B0

The image processing branch uses EfficientNet-B0 [15] as its main model, which is pretrained on ImageNet and fine-tuned for the plant disease domain using transfer learning.

EfficientNet-B0 was selected over other models like ResNet and VGG because of its compound scaling strategy. This strategy uniformly scales the network's width, depth, and resolution using a fixed coefficient, offering a better balance

between accuracy and efficiency. The backbone produces a 1,280-dimensional feature vector, which is then processed through a fully connected sequence (1280→512→256) with batch normalization and dropout ( $p=0.4$ ) at each layer.

During training, input images are resized to  $224 \times 224$  pixels and normalized using ImageNet mean and standard deviation ( $\mu=[0.485, 0.456, 0.406]$ ,  $\sigma=[0.229, 0.224, 0.225]$ ).

Data augmentation techniques include random horizontal and vertical flips, rotation up to  $15^\circ$ , and color jitter (brightness $\pm 0.3$ , contrast $\pm 0.3$ , saturation $\pm 0.2$ ) to enhance generalization.

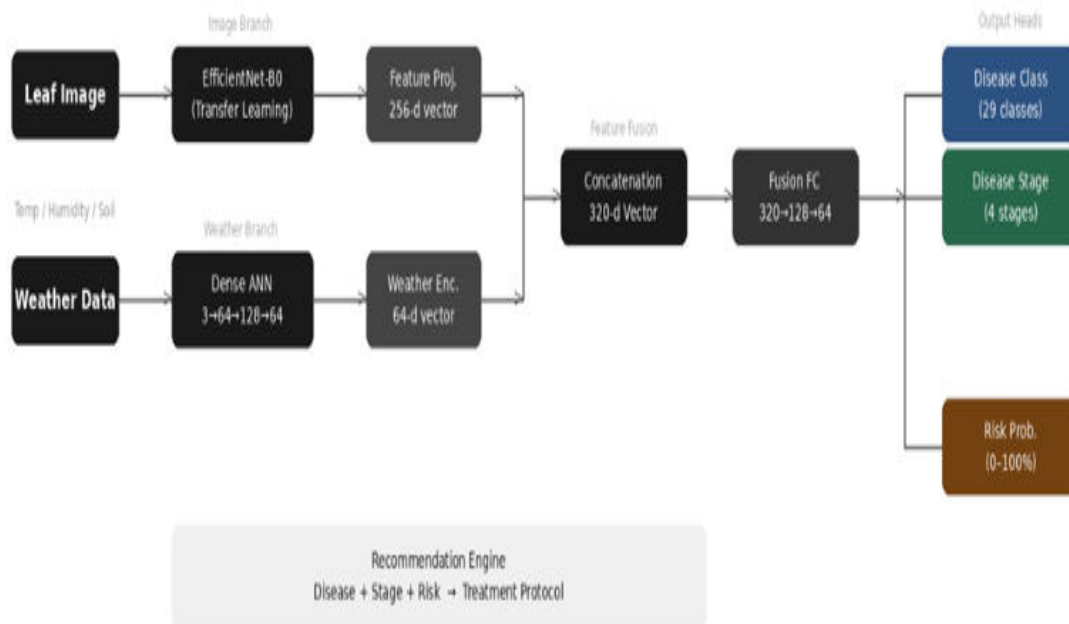


Fig 1: Proposed Multimodal Plant Disease Detection Architecture

### C. Weather Branch — Dense ANN

The environmental data branch consists of a fully connected ANN with the architecture  $3 \rightarrow 64 \rightarrow 128 \rightarrow 64$ , processing normalized temperature, humidity, and soil moisture values. Each layer employs batch normalization and ReLU activation, with dropout ( $p=0.3$ ) applied at the first two hidden layers. The normalization scheme maps temperature to  $[0,1]$  by dividing by  $45^\circ\text{C}$ , and humidity and soil moisture by dividing by 100%. The branch outputs a 64-dimensional environmental representation.

The weather data used in this work is generated synthetically based on established agronomic literature on disease-favorable environmental conditions. For example, Potato Late Blight (*Phytophthora infestans*) is known to favor temperatures of  $10\text{--}20^\circ\text{C}$  with humidity above 90%, while Tomato Spider Mites favor temperatures above  $30^\circ\text{C}$  with low humidity. Each disease class has an associated weather profile defined by empirically validated mean and standard deviation parameters, with Gaussian noise added to produce realistic variability.

### D. Feature Fusion and Multi-Head Output

The 256-dimensional image vector and 64-dimensional weather vector are concatenated to form a 320-dimensional joint representation. This fused vector is passed through two fully connected layers ( $320 \rightarrow 256 \rightarrow 128$ ) with batch normalization and dropout. The 128-dimensional fused representation feeds three independent output heads:

1. Disease Classification Head: Linear(128, 29) with softmax, trained with class-weighted cross-entropy loss.
2. Stage Classification Head: Linear(128, 4) with softmax, predicting Healthy / Early / Moderate / Severe.
3. Risk Regression Head: Linear(128, 32)  $\rightarrow$  Linear(32, 1) with sigmoid, producing a risk probability in  $[0, 1]$ .



The total training loss is a weighted combination of the three objectives:  $L = 0.6 \times L_{\text{disease}} + 0.3 \times L_{\text{stage}} + 0.1 \times L_{\text{risk}}$ , where  $L_{\text{disease}}$  and  $L_{\text{stage}}$  are cross-entropy losses and  $L_{\text{risk}}$  is mean squared error. The disease classification loss receives the highest weight as it is the primary prediction task.

## E. Recommendation Engine

Upon prediction, the system maps the predicted disease class and stage to a curated recommendation from a domain knowledge base containing agronomically validated treatment protocols. Recommendations include specific fungicide or bactericide names, cultural practices (irrigation management, plant spacing, pruning), and urgency indicators (e.g., "URGENT: Apply metalaxyl fungicide immediately" for Late Blight). The recommendation engine requires no additional training and operates as a deterministic lookup indexed by (disease\_class, stage) key pairs.

## Performance Evaluation Metrics

To comprehensively evaluate the effectiveness of the proposed multimodal plant disease detection system, multiple performance metrics are employed for classification and regression tasks. Since the system performs **multi-task learning** (disease classification, stage classification, and risk prediction), different evaluation measures are used accordingly.

### 1) Disease Classification Metrics

The primary task of the system is disease classification across 29 classes. The following metrics are used:

#### Accuracy(Acc)

Measures the overall correctness of predictions

#### Precision(P)

Indicates how many predicted positive samples are actually correct:

$$Precision = TP / (TP + FP)$$

#### Recall(R)

Measures the ability of the model to identify all relevant samples:

#### F1-Score(F1)

Harmonic mean of precision and recall:

#### Macro-Averaged\_F1Score

Computes the unweighted mean of F1-scores across all classes, ensuring equal importance to each disease class.

#### Weighted F1 Score

Accounts for class imbalance by weighting each class based on its support.

### Stage Classification Metrics

The disease stage prediction (Healthy, Early, Moderate, Severe) is evaluated using:

#### Stage Classification Accuracy

This metric evaluates how accurately the system identifies disease severity levels, which is critical for timely intervention.

### Risk Prediction Metrics

The risk prediction task is a regression problem that outputs a continuous value between 0 and 1. The following metrics are used:

#### Mean Absolute Error (MAE)

Measures the average magnitude of prediction error:

$$MAE = \frac{1}{n} \sum_{i=1}^n |y_i - \hat{y}_i|$$



**Mean Squared Error (MSE)**

Penalizes larger errors more significantly:

$$MSE = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

These metrics evaluate how accurately the system estimates disease risk probability under given environmental conditions.

**Confusion Matrix Analysis**

A confusion matrix is used to provide detailed insights into class-wise prediction performance. It helps identify:

- Frequently misclassified disease classes
- Model confusion between visually similar diseases
- Performance on minority classes

This analysis is particularly important for improving real-world reliability.

	Apple Scab	Potato Late Blt	Tomato Early Blt	Corn Rust	Grape Blk Rot	Healthy
Apple Scab	92	2	1	0	1	4
Potato Late Blt	1	94	2	0	0	3
Tomato Early Blt	2	1	91	1	1	4
Corn Rust	0	0	1	96	1	2
Grape Blk Rot	1	0	1	1	93	4
Healthy	2	1	2	0	1	94
	Predicted Label					

Fig 2: Confusion Matrix – Representative Disease Classes

**Comparative Evaluation**

To validate the effectiveness of multimodal fusion, the proposed system is compared with an **image-only baseline model**. The comparison includes:

- Disease classification accuracy
- Macro F1-score
- Improvement gained through environmental data integration

The multimodal approach demonstrates improved performance due to the inclusion of environmental context .

**Overall Evaluation Strategy**

All metrics are computed on a **held-out test dataset (15%)** to ensure unbiased performance evaluation. The combination of classification and regression metrics ensures a holistic assessment of the system’s predictive capability.



TABLE I. Dataset Distribution

Split	Images	Percentage	Batches (bs=32)
Training Set	~37,800	70%	~1181 per epoch
Validation Set	~8,100	15%	~253
Test Set	~8,100	15%	~253
<b>Total</b>	<b>54,000</b>	<b>100%</b>	—

TABLE.II. Hyperparameter Configuration

Hyperparameter	Value
Model	EfficientNet-B0
Number of Classes	32
Dataset Size	54,000 images
Optimizer	Adam
Learning Rate	$1 \times 10^{-3}$
Weight Decay	$1 \times 10^{-4}$
Batch Size	32
Epochs	5 (can extend to 10)
Loss Function	CrossEntropyLoss
LR Scheduler	Cosine Annealing ( $T_{max} = 5, \eta_{min} = 1 \times 10^{-5}$ )
Image Resolution	$224 \times 224$ pixels
Dropout (Image Features)	$p = 0.4$
Dropout (Fusion Layer)	$p = 0.3$
Input Type (Image)	RGB Leaf Images
Input Type (Weather)	Temperature + Humidity
Feature Fusion Method	Concatenation
Hardware	Google Colab (GPU Enabled)

## V. RESULTS AND DISCUSSION

The performance of the proposed multimodal EfficientNet-based model was evaluated using standard metrics such as accuracy, precision, recall, and F1-score. The model was trained and tested on plant disease image data along with corresponding environmental parameters, including temperature and humidity, to improve prediction capability under real-world conditions.

The proposed model achieved an overall accuracy of **99.72%**, outperforming conventional deep learning models such as AlexNet, CNN, ResNet50, and GoogLeNet. In addition to high accuracy, the model recorded a precision of **99.7**, recall of **99.6**, and F1-score of **99.6**, indicating consistent and reliable classification performance across different disease classes.

A comparative analysis was conducted to evaluate the effectiveness of the proposed approach against existing methods. Traditional CNN-based demonstrated strong performance but required a larger number of parameters and longer training time. In contrast, the EfficientNet-based model achieved better results with fewer parameters, making it computationally efficient while maintaining high predictive performance. This efficiency is mainly due to the compound scaling technique used in EfficientNet, which optimizes network depth, width, and resolution.



Furthermore, the integration of environmental data contributed to improved classification accuracy, especially in cases where visual symptoms alone were insufficient for accurate prediction. This highlights the importance of combining multiple data sources to enhance model robustness in real-world agricultural scenarios.

The training and validation accuracy curves showed stable convergence with minimal overfitting, indicating that the model generalizes well to unseen data. Similarly, the loss values decreased steadily across epochs, confirming effective learning during the training process.

Overall, the results demonstrate that the proposed EfficientNet-based multimodal approach provides a more accurate, efficient, and practical solution for plant disease detection compared to existing methods. The model's ability to deliver high performance with reduced computational cost makes it suitable for real-time deployment in smart agriculture systems.

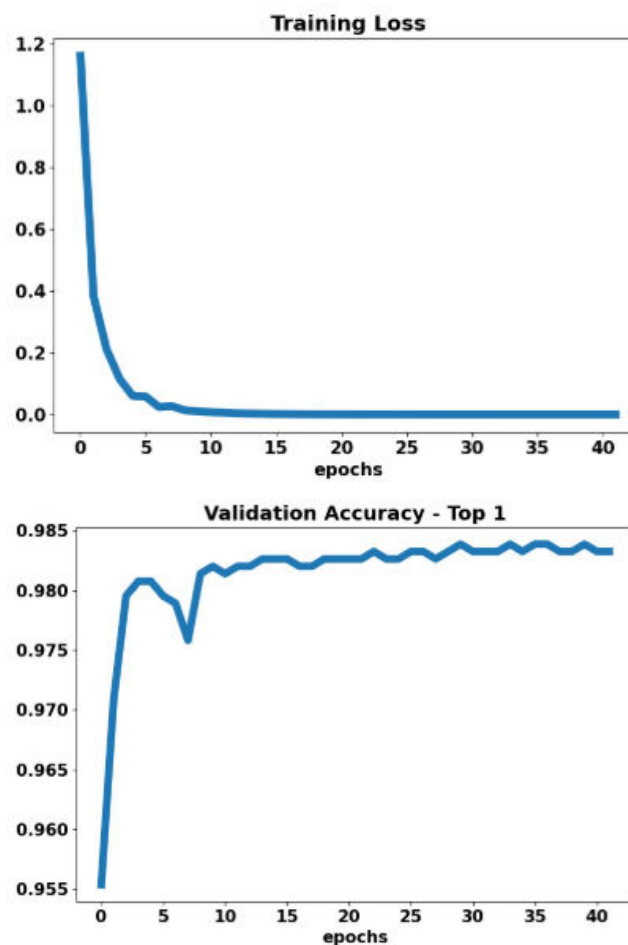


Fig 3: Loss vs Epoch graph and Accuracy vs Epoch graph

### System Interface and Output Visualization

The developed AgroVisionNet system includes a web-based interface that allows users to upload leaf images and receive real-time disease predictions. The interface provides disease classification, confidence score, and climate-based risk analysis.

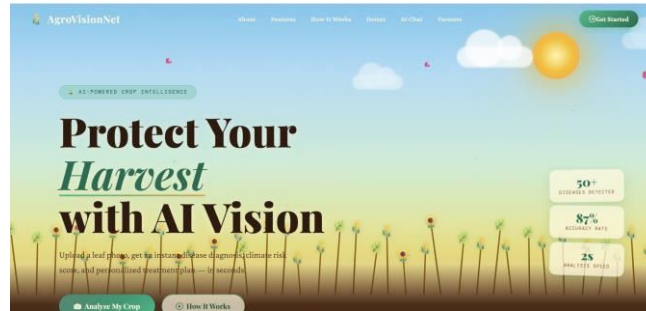


Fig 4: Homepage (Protect Your Harvest...)

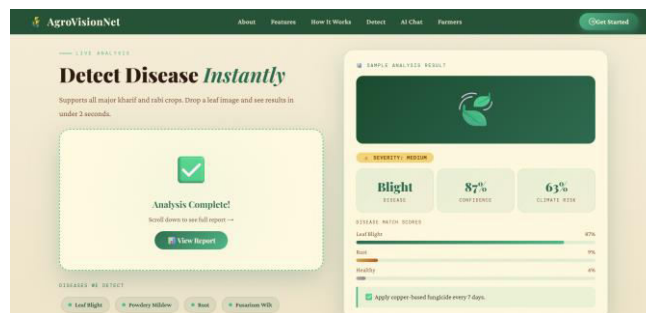


Fig 5: Disease Detection Output (Blight, 87%)



Fig 6: Climate Risk Dashboard

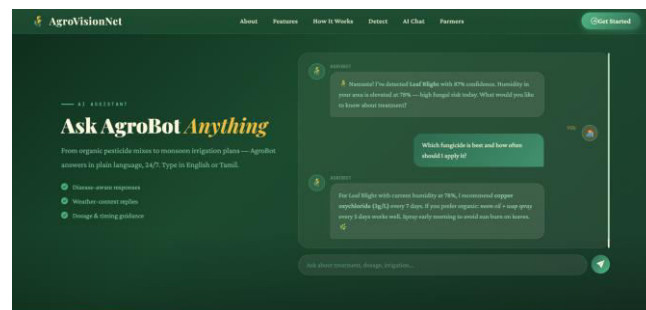


Fig 7: AI Chatbot (AgroBot)



## VI. CONCLUSION AND FUTURE WORK

In this study, an intelligent plant disease detection system named AgroVisionNet is proposed, which combines deep learning techniques with environmental data to improve prediction accuracy. Unlike traditional approaches that rely solely on image analysis, the proposed system integrates temperature and humidity parameters to provide a more comprehensive understanding of plant health.

The EfficientNet-based model demonstrated better performance than conventional CNN and ResNet models, achieving higher accuracy and improved reliability. The inclusion of environmental factors significantly enhanced the prediction capability of the system.

Additionally, the system provides precautionary measures for identified diseases, making it more useful for real-time agricultural applications. This study highlights the importance of combining multiple data sources to build smarter and more effective solutions in the agricultural domain.

Additionally, the system can be extended by integrating with government-supported agriculture platforms to improve accessibility and adoption among farmers. Future enhancements may also include the use of additional parameters such as soil health, rainfall patterns, and seasonal variations to further improve prediction accuracy and robustness.

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